

Is there life between MAK and NAM?

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The Euler-Poisson system

$$\begin{aligned}\partial_\tau v + (v \cdot \nabla)v &= -\frac{3}{2\tau}(v + \nabla\phi) \\ \partial_\tau \rho + \nabla \cdot (\rho v) &= 0 \\ \nabla^2 \phi &= \frac{\rho - 1}{\tau}\end{aligned}$$

Notation of Brenier et al (MNRAS, 2003):

- coordinates comoving with expansion
- τ the growth factor

The variational principle

$$\frac{1}{2} \int_0^T d\tau \int d^3x \tau^{3/2} \left(\rho |v|^2 + \frac{3}{2} |\nabla\phi|^2 \right) \rightarrow \min$$
$$\rho(\mathbf{x}, \tau = 0) = 1, \quad \rho(\mathbf{x}, \tau = T) = \rho_T(\mathbf{x})$$

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“Kicking”

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“Kicking”

$$\begin{aligned} & \frac{1}{2} \int_0^{\tau_k} d\tau \int d^3x \tau^{3/2} \rho |v|^2 \\ & \quad + \frac{1}{2} \tau_k^{3/2} \int d^3x \frac{3}{2} |\nabla\phi|^2 \\ & \quad + \frac{1}{2} \int_{\tau_k}^T d\tau \int d^3x \tau^{3/2} \rho |v|^2 \end{aligned}$$

The minimization strategy

The principal unknown is the map

$$\mathbf{x}|_{\tau=\tau_k} \mapsto X_T(\mathbf{x})|_{\tau=T}$$

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ρ, ϕ at τ_k follow easily:

$$\begin{aligned}\rho(\mathbf{x}, \tau_k) &= \det(\partial_{x_i} \partial_{x_j} X_T) \rho_T(X_T(\mathbf{x})) \\ \nabla^2 \phi(\mathbf{x}, \tau_k) &= \frac{\rho - 1}{\tau_k}\end{aligned}$$

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Kinetic integral between τ_k and T :

$$\begin{aligned} \min \frac{1}{2} \int_{\tau_k}^T d\tau \int d^3x \tau^{3/2} \rho |v|^2 \\ = \frac{1}{2} \int d^3x \rho(\tau_k, \mathbf{x}) |X_T(\mathbf{x}) - \mathbf{x}|^2 \end{aligned}$$

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Kinetic integral between 0 and τ_k vanishes after minimization!

$$\min \int_0^{\tau_k} d\tau \int d^3x \tau^{3/2} \rho |v|^2 = 0$$